

Simplicial Homology

I: Simplices

II: Simplicial Complexes

III: Fields versus Principal Ideal Domains (PID)

IV: Homology: detecting “nice” holes

Reference: J.R. Munkres, “Elements of Algebraic Topology”, Perseus Publishing, 1984, ISBN 0-201-62728-0.

I: Simplices

Definition:

Let $\{a_0, a_1, \dots, a_k\}$ be points in \mathbb{R}^n . This set is said to be geometrically independent if the vectors

$$a_1 - a_0, \quad a_2 - a_0, \quad \dots, \quad a_k - a_0$$

are linearly independent (as in linear algebra).

Remark: We impose that singletons be considered geometrically independent.

Definition:

Let $\{a_0, a_1, \dots, a_k\}$ be a geometrically independent set in \mathbb{R}^n . A k -simplex σ spanned by these points is the set of points $x \in \mathbb{R}^n$ such that

$$x = \sum_{i=0}^k t_i a_i \quad \text{where} \quad \sum_{i=0}^k t_i = 1$$

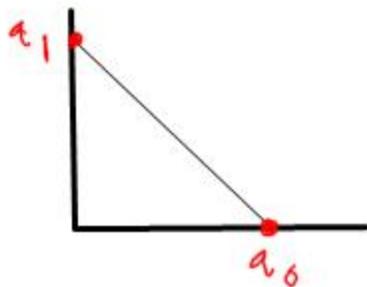
and $t_i \geq 0$ for all i .

Remark: A k -simplex spanned by a_0, a_1, \dots, a_k is the **convex hull** of these points.

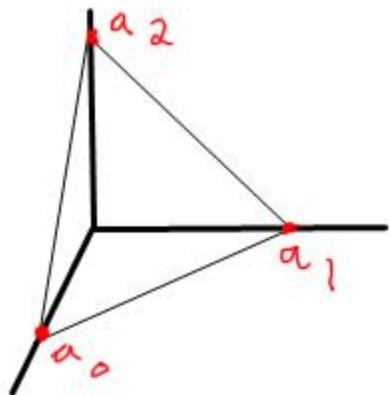
Examples:



0 - simplex



1 - simplex



2- simplex

Let σ be a k -simplex spanned by $\{a_0, a_1, \dots, a_k\}$.

Definition:

1. The points a_0, a_1, \dots, a_k are called the **vertices** of σ .
2. The number k is the **dimension** of σ .
3. Any simplex spanned by a subset of $\{a_0, a_1, \dots, a_k\}$ is called a **face** of σ .
4. The face spanned by $\{a_0, a_1, \dots, a_k\} - \{a_i\}$ for some i is called the **face opposite** to a_i .

II: Simplicial Complexes

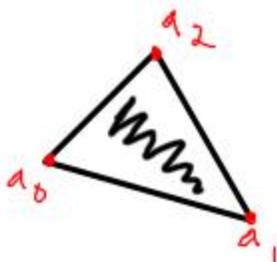
Definition:

A simplicial complex K in \mathbb{R}^n is a collection of simplices in \mathbb{R}^n (of possibly varying dimensions) such that

1. Every face of a simplex of K is in K .
2. The intersection of any two simplices of K is a face of each.

Examples:

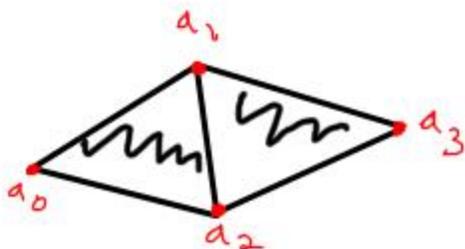
K1:



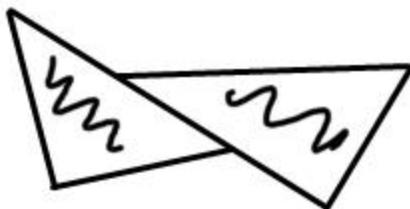
this 2-simplex together with all its faces is a simplicial complex.

$$\left\{ \{a_0, a_1, a_2\}, \{a_0, a_1\}, \{a_0, a_2\}, \{a_1, a_2\}, \{a_0\}, \{a_1\}, \{a_2\} \right\}$$

K2:

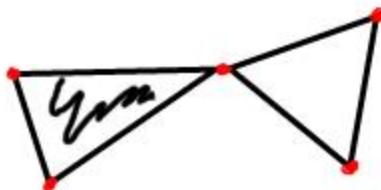


K3:



Is not a simplicial complex

K4:



Is a simplicial complex

Definition:

If L is a subcollection of K that contains all faces of its elements, then L is a simplicial complex. It is called a subcomplex of K

Remark: Given a simplicial complex K , the collection of all simplices of K of dimension at most p is called the p -skeleton of K and is denoted $K^{(p)}$.

e.g. $K^{(0)}$ is the set of vertices of K .

Definition:

If there exists an integer N such that

$$K^{(N-1)} \neq K \quad \text{and} \quad K^{(\geq N)} = K,$$

then K is said to have dimension N . Otherwise it is said to have infinite dimension.

Remark: A simplicial complex K is said to be finite if $K^{(0)}$ is finite.

Topology:

Let K be a simplicial complex in \mathbb{R}^n and consider the set

$$|K| = \bigcup_{\sigma \in K} \sigma.$$

There are two natural ways of putting a topology on $|K|$:

1) $|K|$ being a subset of \mathbb{R}^n , the subspace topology would be a natural choice.

2) Giving each simplex σ of K its natural topology as a subspace of \mathbb{R}^n , declare a subset A of $|K|$ to be **closed** if

$$A \cap \sigma$$

is closed in σ for all $\sigma \in K$.

Remarks:

1. The set $|K|$ together with the second topology is the **realization** of K .
2. In general the second topology is finer (larger) than the first one.
3. These two topologies coincide for finite simplicial complexes.

Example:

Consider the following simplicial complex of the real line:

$$K = \{[n, n+1]\}_{n \neq 0} \cup \left\{ \left[\frac{1}{n+1}, \frac{1}{n} \right] \right\}_{n \in \mathbb{Z}^+}.$$

Clearly, as sets, $|K| = \mathbb{R}$, but **NOT** as topological spaces,

e.g., the set $\left\{ \frac{1}{n} \right\}_{n \in \mathbb{Z}^+}$ is closed in $|K|$ but not in \mathbb{R} .

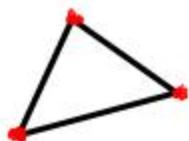
Definition:

A triangulation of a topological space X is a simplicial complex K together with a homeomorphism

$$|K| \longrightarrow X.$$

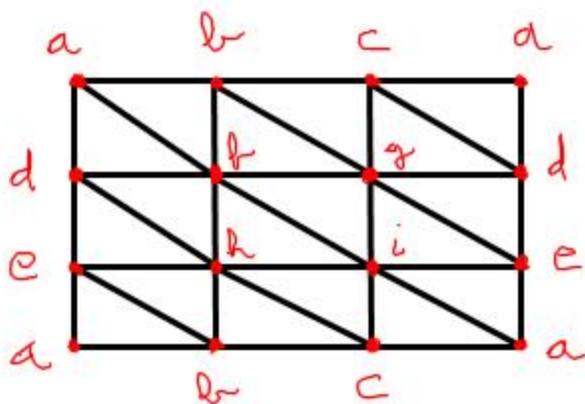
Examples:

K1:

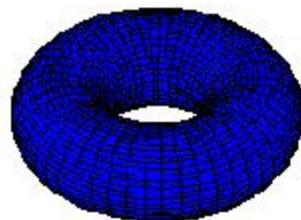


$|K1|$ is homeomorphic to the circle

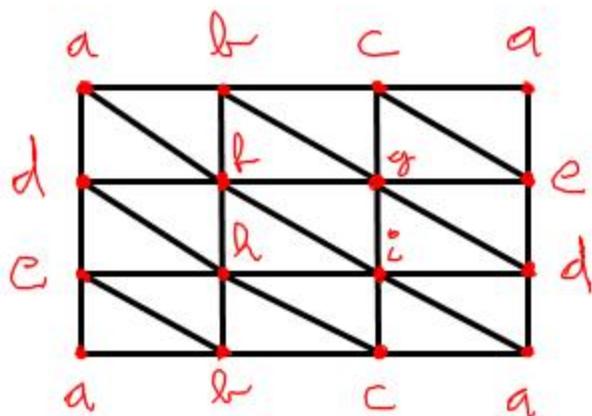
K2:



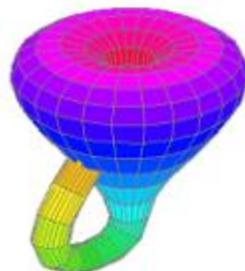
$|K2| =$



K3:



$|K3| =$



III: Fields versus Principal Ideal Domains (PID)

Review:

Let R be a commutative ring with unity 1.

Remark: The ring R is an integral domain if it has no zero divisors.

A. Fields

Let R be a field and V and W be two finite dimensional R -vector spaces. Consider an R -linear map

$$T : V \rightarrow W.$$

Theorem A: If $\dim(V) = \dim(W)$, then the following are equivalent

1. T is injective.
2. T is surjective.
3. T is an isomorphism.

Theorem B: The $\text{Im}(T)$ and $\text{Coker}(T)$ determines W , i.e.,

$$W \cong \text{Im}(T) \oplus \text{Coker}(T).$$

B. PIDs

Recall that a ring R is a PID if it is an integral domain and every ideal in R is principal, i.e., each ideal in R has a generating set consisting of a single element. Thus we have greatest common divisors (gcd's).

e.g., the integers: \mathbb{Z} .

Theorem C: If R is a field, then $R[x]$ is a PID.

Theorem D: If R is a PID and M is a free R -module, then any submodule N of M is free. Moreover, its rank is less than or equal to the rank of M .

Remarks:

1. When R is a PID, Theorem A is false in general, e.g.,

$$\phi : \mathbb{Z} \xrightarrow{\times 2} \mathbb{Z}$$

is injective as a \mathbb{Z} -linear map but not onto!

2. Theorem B is also false when R is a PID, e.g., consider the same map ϕ as in the preceding example.

$$\mathbb{Z} \not\cong 2\mathbb{Z} \oplus \mathbb{Z}/2\mathbb{Z}.$$

C. Extensions

The last remark opens up a vast subject. Consider two R -modules A and C , and the following diagram

$$A \xrightarrow{i} ? \xrightarrow{p} C.$$

Question: How many different R -modules M (up to isomorphism) can we put in the middle of that diagram such that

1. the map i is injective;
2. the map p is surjective; and
3. $Im(i) = ker(p)$?

Answer: $\text{Ext}(C, A)$

Theorem E: For any abelian group A and positive integer m we have

$$\text{Ext}(\mathbb{Z}/m\mathbb{Z}, A) \cong A/mA.$$

e.g., $\text{Ext}(\mathbb{Z}/2\mathbb{Z}, \mathbb{Z}) = \mathbb{Z}/2\mathbb{Z}$, i.e., there are two possible extensions

$$\mathbb{Z} \xrightarrow{\times 2} \mathbb{Z} \xrightarrow{p} \mathbb{Z}/2\mathbb{Z}$$

and

$$\mathbb{Z} \xrightarrow{i} \mathbb{Z} \oplus \mathbb{Z}/2\mathbb{Z} \xrightarrow{p} \mathbb{Z}/2\mathbb{Z}$$

IV: Homology: detecting “nice” holes

A: Ordered simplices

Let σ be a simplex. Two orderings of its vertex set are equivalent if they differ by an even permutation.

If $\dim(\sigma) > 0$ then the orderings of the vertices of σ fall into two equivalence classes.

Each class is called an orientation of σ .

Definition:

An oriented simplex is a simplex σ together with an orientation of σ .

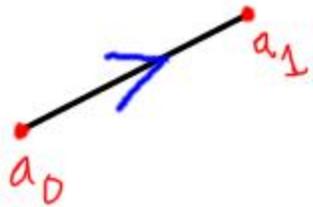
If $\{a_0, a_1, \dots, a_p\}$ spans a p -simplex σ , then we shall use the symbol

$$[a_0, a_1, \dots, a_p]$$

to denote the oriented simplex.

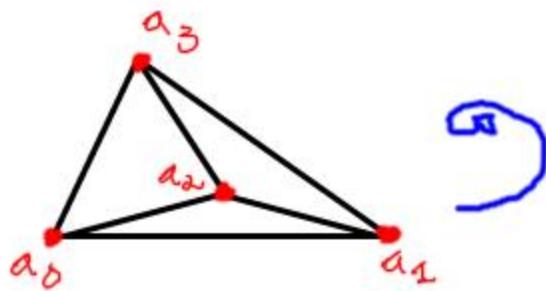
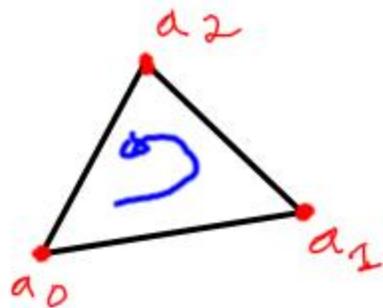
Remark: Clearly 0-simplices have only one orientation.

Examples:



1-oriented simplex

2-oriented simplex



3-oriented simplex

B: p -chains

Let K be a simplicial complex and G an abelian group.

Definition: A p -chain of K with coefficients in G is a function c_p from the oriented p -simplices of K to G that vanishes on all but finitely many p -simplices, such that

$$c_p(\sigma') = -c_p(\sigma)$$

whenever σ' and σ are opposite orientations of the same simplex.

The set of p -chains is denoted by $C_p(K; G)$. Moreover, it carries a natural abelian group structure, i.e, given $c_p, e_p \in C_p(K; G)$ we define

$$(c_p + e_p)(\sigma) = c_p(\sigma) + e_p(\sigma).$$

Remark: If $p < 0$ or $p > \dim(K)$, then we set $C_p(K; G) = 0$.

Special case: $G = \mathbb{Z}$

If σ is an oriented simplex, there is an associated elementary chain c such that

1. $c(\sigma) = 1$;
2. $c(\sigma') = -1$ if σ' is the opposite orientation of σ ; and
3. $c(\tau) = 0$ for all other oriented simplices τ .

Remark: By abuse of notation we will use the symbol σ to represent the associated elementary chain c , i.e.,

$$\sigma' = -\sigma.$$

Theorem F:

$C_p(K; \mathbb{Z})$ is a free abelian group; a basis can be obtained by orienting each p -simplex and using the corresponding elementary chains as a basis.

Definition:

We now define a homomorphism

$$\partial_p : C_p(K; \mathbb{Z}) \rightarrow C_{p-1}(K; \mathbb{Z})$$

called the boundary operator.

Let $p > 0$ and $\sigma = [v_0, \dots, v_p]$ be an oriented simplex. Then

$$\partial_p \sigma = \sum_{i=0}^p (-1)^i [v_0, \dots, \hat{v}_i, \dots, v_p]$$

where \hat{v}_i means that the vertex v_i has been omitted.

Remarks:

1. It is routine to check that ∂_p is well defined.
2. You then extend linearly (using Theorem F) to the full $C_p(K; \mathbb{Z})$.
3. The boundary operators $\partial_{\leq 0}$ are set to 0 since $C_{p<0}(K; \mathbb{Z}) = 0$.

Examples:

1. 1-simplex: $\partial_1[v_0, v_1] = v_1 - v_0.$

2. 2-simplex: $\partial_2[v_0, v_1, v_2] = [v_1, v_2] - [v_0, v_2] + [v_0, v_1].$

3. 3-simplex: $\partial_3[v_0, v_1, v_2, v_3] = [v_1, v_2, v_3] - [v_0, v_2, v_3] + [v_0, v_1, v_3] - [v_0, v_1, v_2].$

Remark: Notice that $\partial_1 \circ \partial_2 = 0.$

Theorem G: $\partial_{p-1} \circ \partial_p \equiv 0.$

Analogy with calculus

Analysis

Geometry

Dim 0:

$C^\infty(\mathbb{R}^3)$

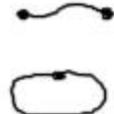
points



Dim 1:

C^∞ -vector field
on \mathbb{R}^3

curves



Dim 2:

C^∞ -vector field
on \mathbb{R}^3

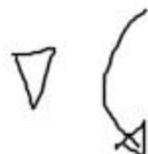
surfaces



Dim 3:

$C^\infty(\mathbb{R}^3)$

volumes

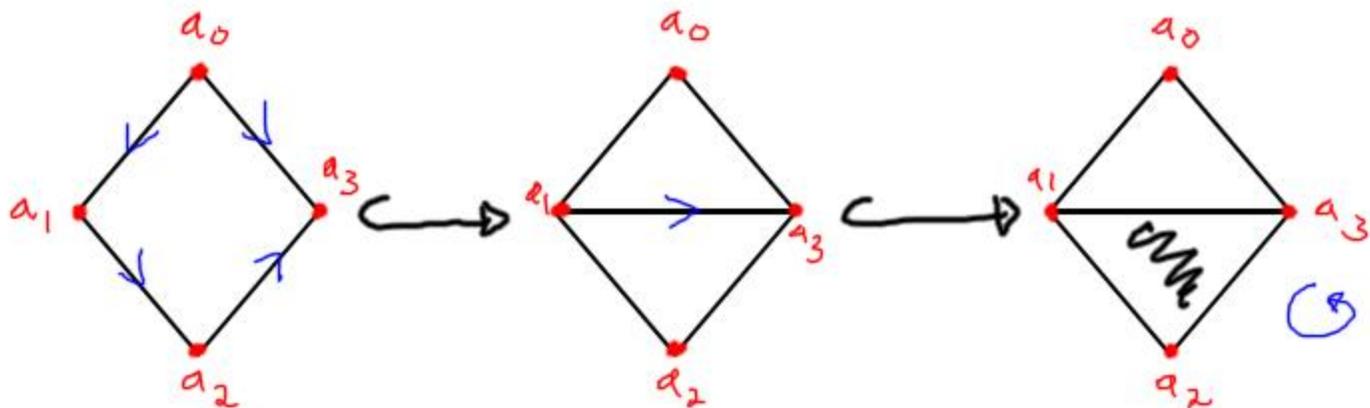


$$\nabla \times \nabla f = 0$$

$$\nabla \cdot \nabla \times F = 0$$

$$\int^2 = \emptyset$$

Detecting Holes: Simplicial Homology



K1

K2

K3

$$C = [a_0 a_1] + [a_1 a_2] + [a_2 a_3] - [a_0 a_3]$$

$$N_1 = [a_0 a_1] + [a_1 a_3] - [a_0 a_3]$$

$$[a_1 a_2 a_3]$$

$$N_2 = [a_1 a_2] + [a_2 a_3] - [a_1 a_3]$$

Some computations:

K_1 : Notice that

$$\partial_1(c) = (a_1 - a_0) + (a_2 - a_1) + (a_3 - a_2) - (a_3 - a_0) = 0.$$

At first sight, $\ker(\partial)$ seems to measure holes.

K_2 : It seems that K_2 has three holes, since $\partial_1(v_1) = \partial_1(v_2) = \partial_1(c) = 0$.

But clearly

$$c = v_1 + v_2,$$

i.e., in K_1 , $\dim(\ker(\partial_1)) = 1$, and in K_2 , $\dim(\ker(\partial_1)) = 2$.

K_3 : c , v_1 , and v_2 are still in K_3 , but v_2 is no longer representing a hole!

How do we get rid of it?

Consider the 2-simplex $[a_1, a_2, a_3]$.

Then

$$\partial_2[a_1, a_2, a_3] = [a_2, a_3] - [a_1, a_3] + [a_1, a_2] = v_2.$$

i.e., $v_2 \in \text{Im}(\partial_2)$.

These observations together with Theorem G ($\partial^2 = 0$), suggest the following.

Definition: Let

1. $Z_k = \ker(\partial_k)$, which we call k -cycles; and
2. $B_k = \text{Im}(\partial_{k+1})$, which we call k -boundaries.

Remark: Theorem G implies that $B_k \subset Z_k$.

Then the k^{th} -homology group of K is

$$H_k(K; \mathbb{Z}) = Z_k / B_k.$$

Summary:

1. $H_1(K_1) \cong \mathbb{Z}$;
2. $H_1(K_2) \cong \mathbb{Z} \oplus \mathbb{Z}$; and
3. $H_1(K_3) \cong \mathbb{Z}$. The cycles c and v_1 in K_3 actually represent the same homology class, i.e., they differ by a boundary namely,

$$v_1 = c - \partial[a_1, a_2, a_3].$$

The effect of changing coefficients

Let T denote the torus and K the Klein bottle.

1. One can show that over \mathbb{Z}

$$H_1(T; \mathbb{Z}) \cong \mathbb{Z} \oplus \mathbb{Z} \quad \text{and} \quad H_2(T; \mathbb{Z}) \cong \mathbb{Z},$$

while

$$H_1(K; \mathbb{Z}) \cong \mathbb{Z} \oplus \mathbb{Z}/2\mathbb{Z} \quad \text{and} \quad H_2(K; \mathbb{Z}) = 0.$$

2. If one considers $\mathbb{Z}/2\mathbb{Z}$ -coefficients, then

$$H_1(T; \mathbb{Z}/2\mathbb{Z}) \cong \mathbb{Z}/2\mathbb{Z} \oplus \mathbb{Z}/2\mathbb{Z} \cong H_1(K; \mathbb{Z}/2\mathbb{Z})$$

and

$$H_2(T; \mathbb{Z}/2\mathbb{Z}) \cong \mathbb{Z}/2\mathbb{Z} \cong H_2(K; \mathbb{Z}/2\mathbb{Z})$$